

ECI (EN-3212)- Electronics (& Computer Integration)

Electronics - SPRING 2016 (STCW)

ECI provides a broad overview of the modern electronics used by the marine and power industries for automation, system monitoring and control. Electronic components and circuits are categorized by function (sensor, transmitter, actuator or controller), signal type (analog or digital), and technology (i.e., computer, micro-electronic, solid-state).

Engineering Learning Outcomes:

1. Understand the relationship of component blocks and signals in electronic systems.
2. Define and analyze circuits and components used for analog signals and conditioning.
3. Define and analyze circuits and components used for digital signals and conditioning.
4. Read analog and digital circuit diagrams, and identify basic electronic components.
5. Use solid-state devices (Op-Amps) for both amplification and switching applications.
6. Read and understand PLC and ladder logic circuits used in discrete-state applications.

STCW Demonstrated Knowledge, Understanding & Proficiency:

OICEW-B1.2 Configuration and operation principles of electronic equipment

OICEW-B1.2 Characteristics of basic electronic circuit elements

OICEW-B2.6 The interpretation of electrical and simple electronic diagrams

Text: **Process Control Instrumentation Technology**
Curtis D. Johnson, 8th Edition (© 2006), Prentice Hall

Instructor: Dr. John J. Bausch Phone: (508) 830-5000 (x-2029)
Email: jbausch@maritime.edu Room: HA 222

Email & Calendar: Check your email **DAILY** for **electronic assignments**, additional information, and the Electronics Class Calendar (iCal on Macs, Outlook, and Google):

Class: Monday, Wednesday, and Friday
Sections x13 = @1000 (2nd period)
Room: BR 222 (see my ELab Hours for extra help)

Grading: Grades are based on homework, quizzes, and exams. The 2-hour final is comprehensive. Attendance is noted and graded. **Late work will NOT be accepted.**

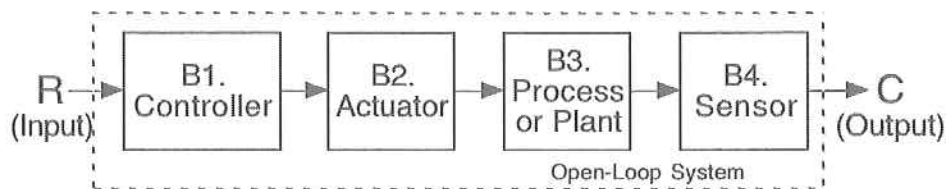
STCW Requirements: A minimum grade of **C- (70 out of 100)** is needed to **PASS ATTENDANCE** is mandatory and will be tracked to satisfy the STCW requirements.

Evaluation: Exam problems are based primarily on homework and quizzes.

Homework (~weekly)	5%
iClicker Feedback (daily)	5%
Quizzes (any time)	20%
Exam1	20%
Exam2	20%
Final (2 hour Comprehensive)	30%
<hr/> Total Grade	<hr/> 100%

ECI- Electronics & Computer Integration

ECI now uses the textbook previously used for Instrumentation & Control: Curtis Johnson's "Process Control Instrumentation Technology". Using the first eight chapters, students are exposed to most of the electronic hardware components and systems in use in both analog and digital worlds. The C-A-P-S diagram below is used to introduce students to the concept of block-diagram systems, and the input/ output relationships of most industrial electronic components. Electronic hardware components are defined first by electronic function as one of the following: 1) a Controller, 2) an Actuator, or 3) a Sensor, as related to a Process, Plant or system.

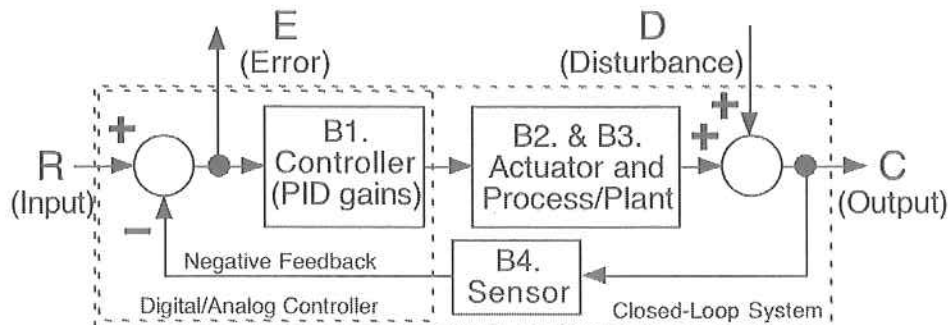


ECI-Electronics: The C-A-P-S Model; the open-loop Block Diagram that defines major components of Electronic Hardware, and the relationship between the electrical signals.

INC (EN-4223)- Instrumentation & Controls

Modern digital controllers are primarily implemented in software and require more advanced dynamic system models; real-time signals are integrated through programs like Matlab/Simulink (introduced in INC) using C-language-like .m files. The INC class takes the component block diagram from ECI (shown above), and adds the complexity of a closed-loop, multi-input, multi-output, PID controller (shown below). In this case, the system dynamics are essential to design, and the INC class introduces controller performance parameters based on:

1) Stability, 2) Speed of Response, and 3) Dynamic Accuracy.



INC-Controls: The Closed-loop Block Diagram for Instrumentation & Controls. INC uses transfer functions to study the more advanced concepts of dynamic modeling and multi-input, multi-output, proportional-integral-derivative (PID) control systems.

ECI-2010 SAMPLE Schedule-NOT ACTUAL!!!
(The real-time electronic schedule, is sent via email)

NOTE: This is Not the ACTUAL Syllabus. Check your email for the iCal Link.

- L1: Welcome to ECI
- L2: Intro to Marine Electronics
- L3: Electronic Control Applications
- L4: Intro to Control Systems
- L5: Control System Performance
- L6: Digital & Analog Systems
- L7: Levels of Control Electronics
- L8: Measurement Units & Error
- L9: Error, Accuracy & Uncertainty
- L10: Sensors & System Dynamics
- L11: Intro to Analog Signal Processing
- L12: Filtering & Impedance
- L13: Voltage Dividers & Bridges
- L14: RC (Analog) Filters
- L15: RC Filter Design
- L16: Exam1 Review
- L17: 1st Order & 2nd Order Hi-Pass Filters
- L18: Advanced RC Filter Design
- L19: Filter Design with Op-Amps
- L20: Intro to Operational Amplifiers
- L21: Op-Amp Electronic Circuits
- L22: Intro to Digital Signal Processing
- L23: Boolean Algebra & Logic Gates
- L24: Digital PLCs (Programmable Logic Controllers)
- L25: Digital Electronics & Devices
- L26: Digital to Analog Converters (DACs)
- L27: Analog to Digital Converters (ADCs)
- L28: Exam2 Review
- L29: Guest Lecture: Mr. Tom Quinn from Rolls Royce Marine
- L30: Intro to Ladder Logic & PLC Systems
- L31: Switching Theory & Boolean Logic
- L32: Ladder Logic System Design
- L33: E-M Relay Timer Design
- L34: Cargo Elevator Application Case Study
- L35: Intro to Industrial PLCs
- L36: PLC Programming
- L37: Transistors & Solid-State Relays
- L38: ECI Course Review
- L39: Final Exam

Problem Set #1:

ECI- PSet1 Due Friday, 11Mar16

Reading: Chapter 1 in Johnson (Sections 1.1-1.4)

Problems:

1.1- A/C System, Block Diagram

1.2- Auto Driving Control

Is this open-loop or closed-loop?

What are the sensors?

1.3- Refer Madness. Chill out with another Block Diagram.

1.4- Control Performance Criteria: Max Error and Settling Time

1.5- System Tuning

1.6- Quarter Amplitude Criterion

1.7- Quarter Amplitude Criterion again
